What You Didn't Know about GPS and Its Augmentations

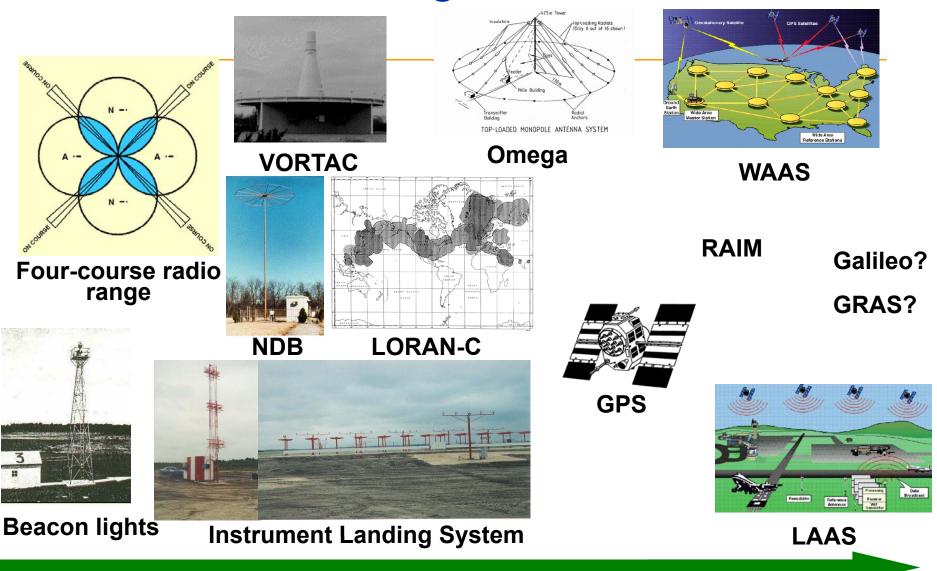
Vince Massimini Rick Niles

June 2009

Overview

- GPS accuracy and integrity
- GPS and augmented GPS services
- GPS legalities
- GPS procedures (and plans for future procedures)
- Area Navigation (RNAV) and Required Navigation Performance (RNP)
- Future GPS and augmentations

Overview - Navigation Aid Evolution



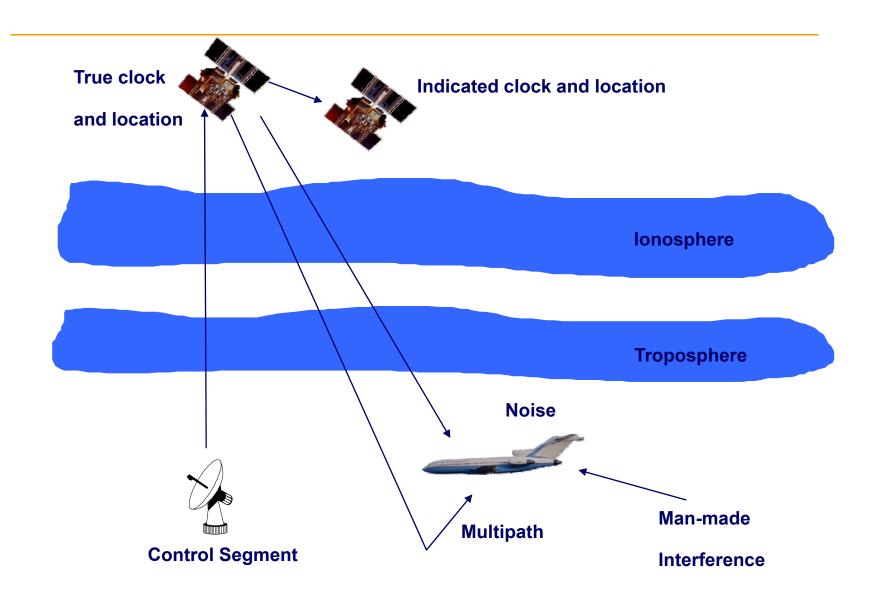
Global Navigation Satellite System (GNSS)

- Global Positioning System (GPS) (U.S.)
 - Nominally 24 satellites in 6 orbital planes inclined 55 degrees
 - Operational for civil aviation since 1994
- GLONASS (Russian)
 - Nominally 21 satellites in 3 orbital planes inclined 45 degrees
 - Uneven sustainment for many years; fully operational in 2009(?)
- Galileo (European Union)
 - Nominally 27 satellites in 3 orbital planes inclined 56 degrees
 - Two test satellites in orbit; Operational in 2013 (?)
- Compass (China)
 - 5 current satellites; proposed mix of GEO and MEO satellites

GPS Constellation

- Nominal constellation is 24 satellites in 6 planes
 - 4 "slots" per orbit
 - Transmit ranging code on single frequency (L1:1575.42 MHz)
- 32 satellites are flying right now (31 operational)
- The U.S. DoD commitment is:
 - > 24 satellites operational 95% of the time
 - Does not mean all 24 have a useable navigation signal
 - ≥ 21 slots filled with at least one satellite transmitting a useable navigation signal 98% of the time
 - ≥ 20 slots 99.999% of the time
- More later on the GAO report

GPS Error Sources



The 1992 Political Slogan: It's the Economy, Stupid!!

But Clinton Never Heard of Integrity

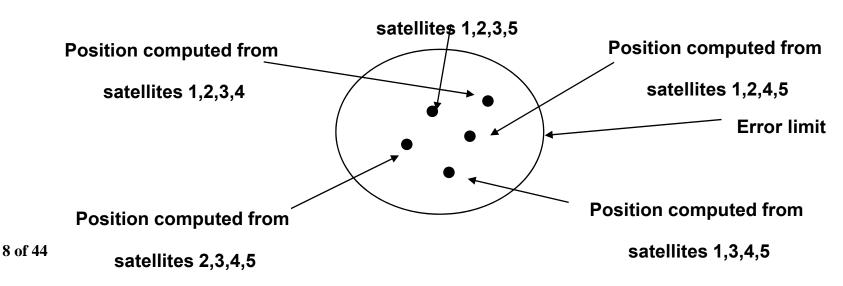
- Accuracy
 - GPS: ~2-3 m horizontal and 4-6 m vertical
- GPS can have major errors (faults)
 - For example, a runaway clock on a GPS satellite could cause thousands of meters of error with no warning
 - Up to 6 hours for USAF to disable navigation signal
 - July 2001—clock problem caused errors of 2,000 3,000 km
- Integrity: Ability of a system to provide service within known limits or to notify the user that the system is out of tolerance.

Augmentation Systems

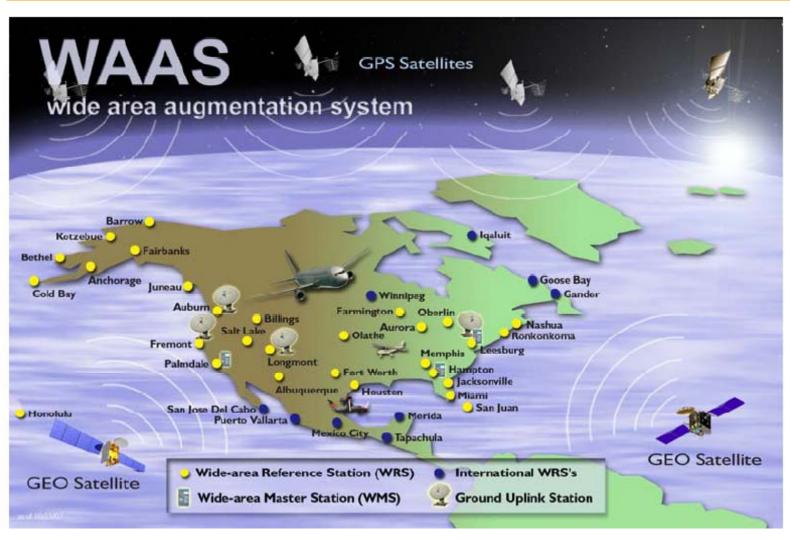
Receiver Autonomous Integrity Monitoring (RAIM)

- Four satellites can provide position and time
- With 5 satellites, users can calculate positions using groups of four and compare the positions
 - Barometric aiding can reduce this to four satellites
- With > six satellites, users can identify and eliminate a bad satellite

Position computed from



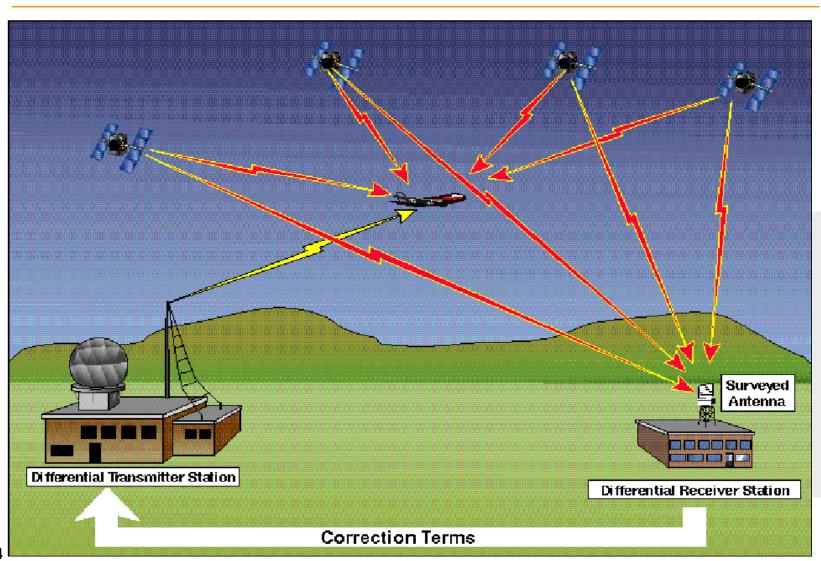
Wide Area Augmentation System (WAAS)



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Source: Federal Aviation Administration

Local Area Augmentation System (LAAS)



What do WAAS and LAAS Do?

Ground stations listen for errors on GPS satellites

WAAS

- Errors from ground stations are transmitted to master stations (3 total master stations) which
 - Compute orbit and clock errors of each satellite
 - Create a grid of ionospheric errors over the U.S.
- A GEO satellite receives and retransmits to users via L1:
 - Orbit and clock errors for each satellite
 - Grid of ionospheric errors
 - Integrity warnings of bad satellites
- The GEO satellite also transmits a GPS-like ranging signal

LAAS

 A total error for each satellite is transmitted to users near the LAAS station via a VHF data link signal

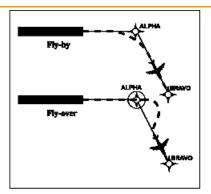
What are the Effects of WAAS and LAAS?

- Extra ranging from Geo satellites
 - Equivalent to 2 4 extra GPS satellites in USA
- Integrity warning is from WAAS or LAAS
 - RAIM is not required (i.e., fewer satellites are required)
- Improved accuracy and integrity
 - Accuracy
 - GPS: ~2-3 m horizontal and 4-6 m vertical
 - WAAS: ~.5 m horizontal and 1 m vertical
 - Integrity (maximum allowable un-alarmed error)
 - GPS LNAV Approach: 556 m integrity limit (horizontal only)
 - WAAS LPV Approach: 40 m horizontal and 50 or 35 m vertical
 - LAAS GLS Approach: 40 m horizontal and 10 m vertical

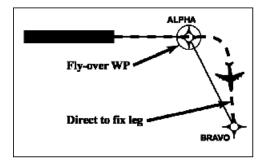
RNAV Benefits/Services

RNAV Leg Types

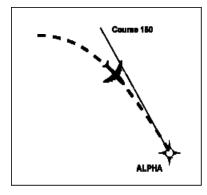
• Track to Fix (TF)



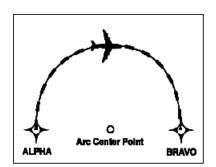
Direct to Fix (DF)



• Course to Fix (CF)

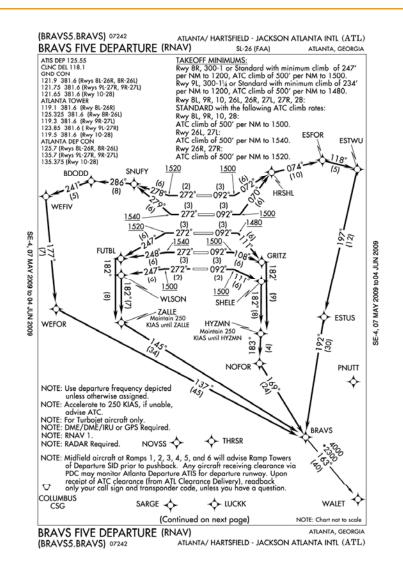


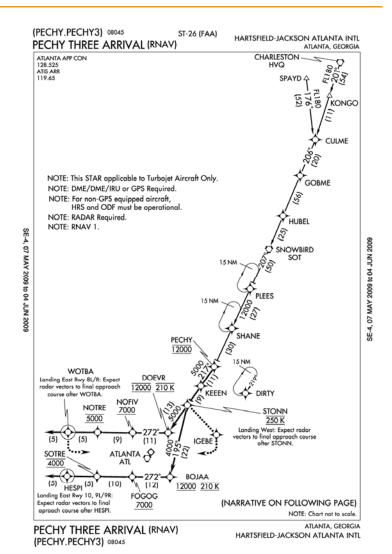
• Radius to Fix (RF)



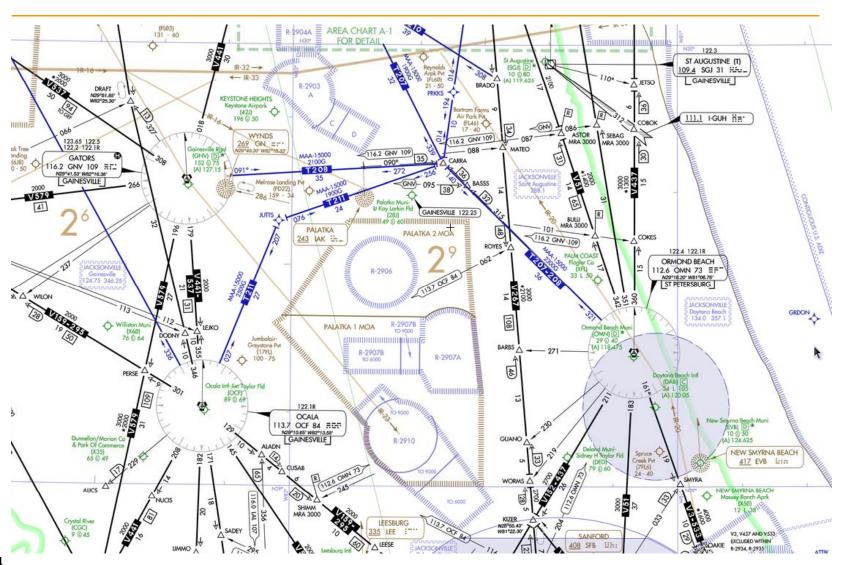
14 of 44 • Heading (VA)

RNAV DPs and STARS

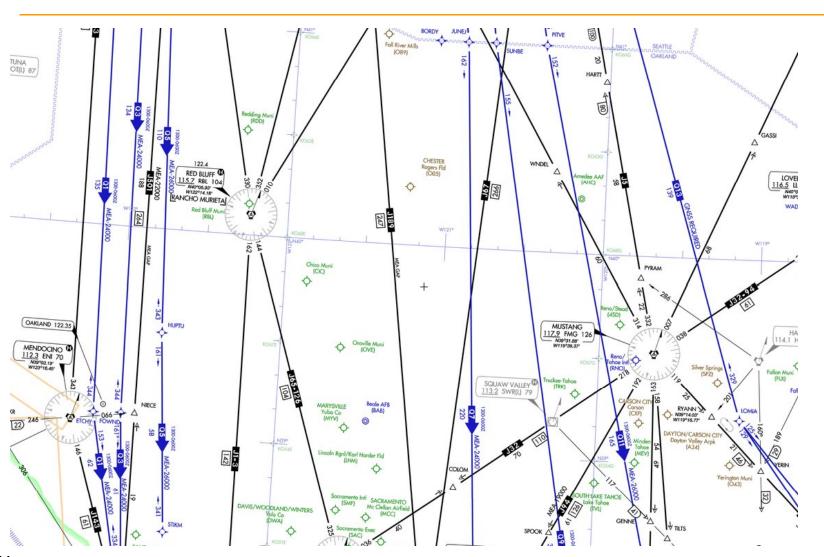




T Routes



Q Routes



File and Fly Direct

- Radar coverage required in CONUS
- Currently FAA automation requires at least one fix in each ARTCC
- Example routes
 - KFME WOOLY V214 MRB CTW I40
 - KFME GRACO V93 PXT V213 TAPPA KCPC
- ATC may clear you direct beyond center boundary to destination
 - Will need "heading to destination"
 - They actually mean ground track bearing

RNAV Approaches

No ground based navigation aids required

LNAV

- WAAS (TSO-145/146) or GPS (TSO-C129) receiver required
- Near 100% availability with WAAS (not with only GPS (TSO-C129)

LNAV/VNAV

 Either WAAS (TSO-145/146) receiver or GPS (TSO-C129) receiver with approved barometric vertical navigation (Baro VNAV) system required

RNAV Approaches

LPV

- WAAS (TSO-145/146) receiver required
- Minimums as low as 200 ft above the touchdown zone
 - Should never be higher than an ILS

• LP

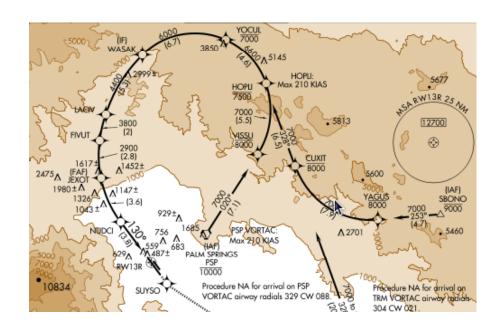
- WAAS (TSO-145/146) receiver required
- Allows for non-precision approach with low minimums
- Used when an obstacle prevents LPV and minimum is at least 20 feet lower than the equivalent LNAV approach
- Required Navigation Performance (RNP)

What is RNP?

- RNP is RNAV with on-board navigation monitoring and alerting
- RNP has a specific "performance level"
 - e.g. RNP 2 means the aircraft will be within 2.0 NM of the centerline of the route 95% of the time
 - This includes the combination of both navigation system performance and flight technical error (pilot error)
- GPS and WAAS receivers are approved for RNP 0.3 and above
 - RNP with Authorization Required (AR) currently approved to RNP 0.1

RNP Approaches

- Standard RNP approach
 - None ever published
- 137 RNP (SAAAR) approaches published (7 May 2009)
 - Valuable for mountainous terrain with curved segments



GPS Legalities

Handheld and VFR Panel Mount GPSs VFR Flight

- GPS use for VFR flight is generally unregulated by the FAA
 - Strictly advisory
 - PIC must ensure that PDAs do not interfere with aircraft systems
- Few, if any, handheld GPSs have integrity monitoring
 - Look out of the window!!
- Panel mount VFR GPSs have no operational differences from handhelds
 - Installed antenna may give better reception

Handheld and VFR Panel Mount GPSs IFR Flight

Advisory use only

- Aircraft must carry appropriate avionics for ground navigation aids to be used in the flight
- No /G equipment code
- Cannot file to RNAV-only waypoints or fly RNAV approaches

Radar vectors can be used

- "Center, request radar vectors to LAX VOR; heading is 277°"
- "N12345 fly heading 277 direct LAX, report receiving"
- "N12345 fly direct WALLO flight plan route"
- "Potomac, N12345 is not RNAV; request vectors to WALLO; heading is 330°"
- "N12345 fly heading 330 direct WALLO

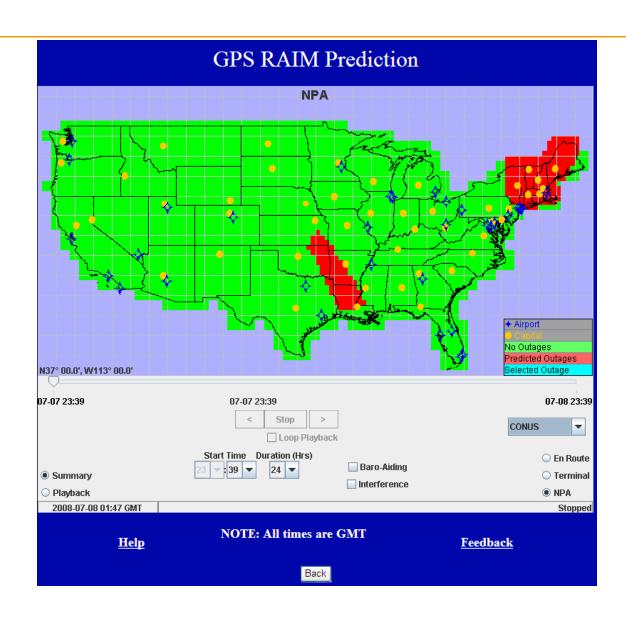
IFR GPS Requirements

- GPS (TSO-C129 (non-WAAS))
 - Installed IAW AC 120-38
 - Must maintain avionics necessary to receive ground based navigation aids (including 30-day VOR check)
- WAAS (TSO 146)
 - Installed IAW AC 120-38a
 - Approved as sole means of navigation
 - No requirement to carry VOR, ILS, ADF, etc. or other avionics necessary to receive ground navigational aids
 - Check AFM—some 430Ws have a temporary restriction
- A current database is required for IFR use
 - Unless the FAA-approved AFM indicates that waypoints can be checked manually

IFR GPS Requirements

- A number of requirements have been changed in the last few years that facilitate GPS use
 - 14CFR 91.131: a VOR is no longer required in Class B airspace--an approved RNAV system is now acceptable
 - GPS can substitute for VOR (airways and waypoints)
- GPS has been an approved substitute for DME and ADF for several years
 - A VOR or NDB approach cannot legally be flown with a GPS--needs to be VOR or GPS/NDB or GPS
 - GPS cannot substitute for ILS or localizer

www.raimprediction.net



IFR GPS Requirements 2 of 2

- WAAS LPV approaches (still!!) cannot be used to satisfy the precision approach requirements in the PTS
 - Rick and I are both working to change this

Preflight

Equipment Codes

- File /G if your aircraft has an IFR qualified GPS panel mounted receiver with current database
 - No equipment code is filed on a VFR flight plan
- Do NOT file /G
 - If your aircraft has only a VFR qualified GPS receiver
 - E.g., N781FM (GX 55)
 - If the database has expired (unless OK by AFM)
 - If you only have a hand-held GPS receiver
- You may file "/R", but it will not do you any good since there are currently no RNP procedures that are not SAAAR.

Preflight Requirements 1 of 2

- Navigation database must be up-to-date
 - Check on preflight
- GPS (TSO-C129) users must check GPS NOTAMS
 - Satellite outage or radio frequency interference
 - Must ask FSS or look online (for KNMH or KGPS)
- WAAS (TSO145/146) user must check WAAS NOTAMS
 - WAAS out of service, WAAS unreliable
- Before a TSO-C129 user flies an RNAV route they must check www.raimprediction.net
 - AC 90-100a
 - Or use manufacturer approved software
- Must file ICAO flight plan if flying an RNAV STAR or DP for both WAAS and GPS

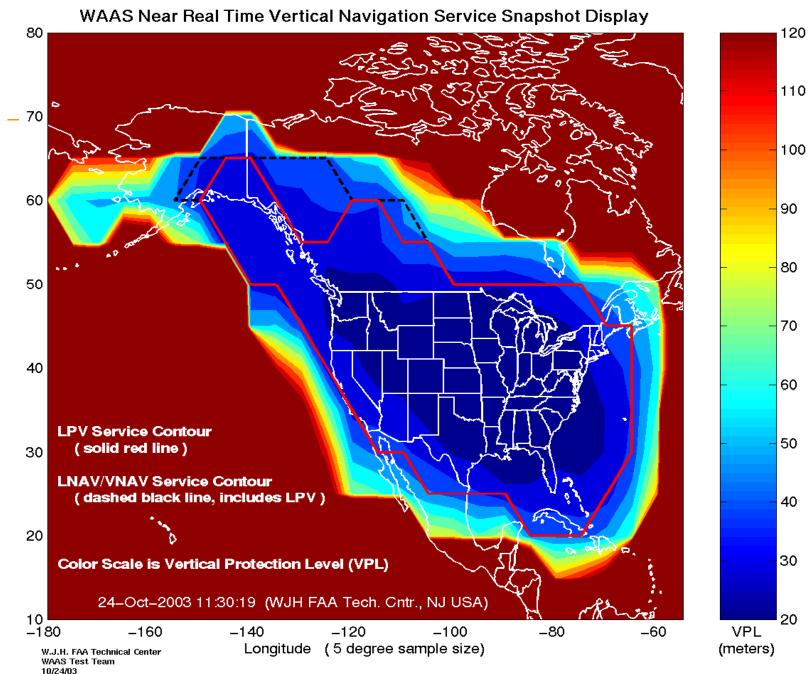
Preflight Requirements 2 of 2

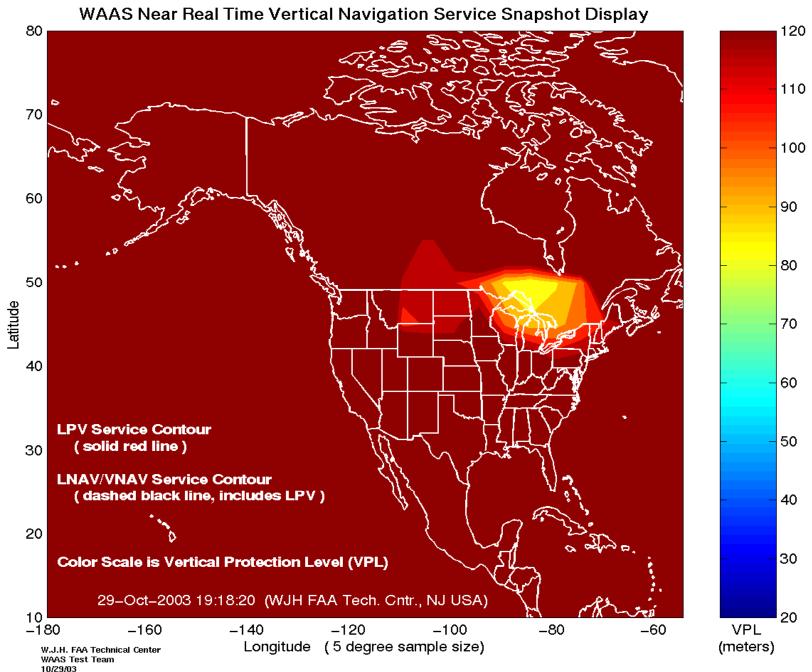
- For GPS (TSO-C129): If an alternate airport is required, an approach must be available that can be flown without the use of GPS
 - Cannot use VOR, DME, or ADF unless approved and operational avionics are installed
 - Does not apply to WAAS (TSO-145) receivers
 - WAAS receivers may plan for LNAV at alternate
 - Except that some of the Garmin 400x series have a temporary flight manual restriction

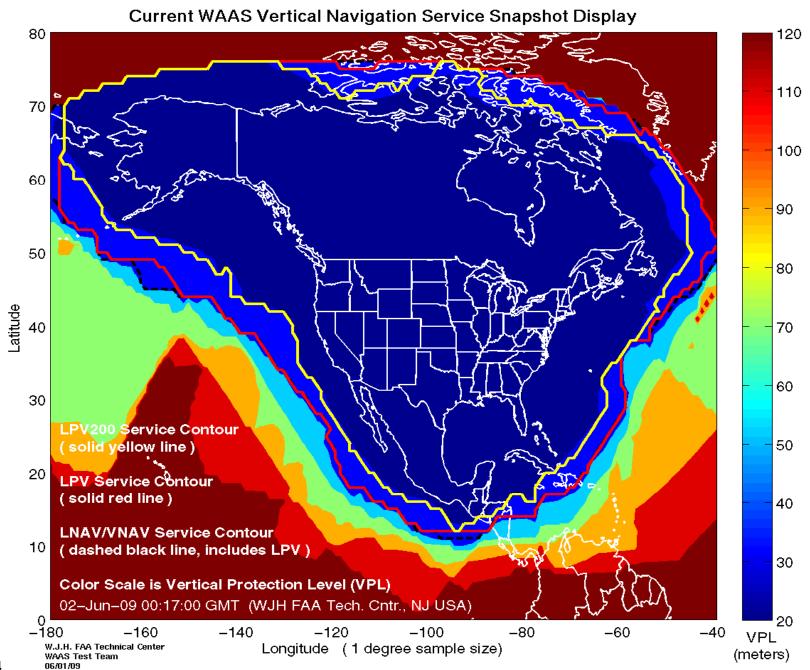
Future GNSS

Dual Frequency GPS

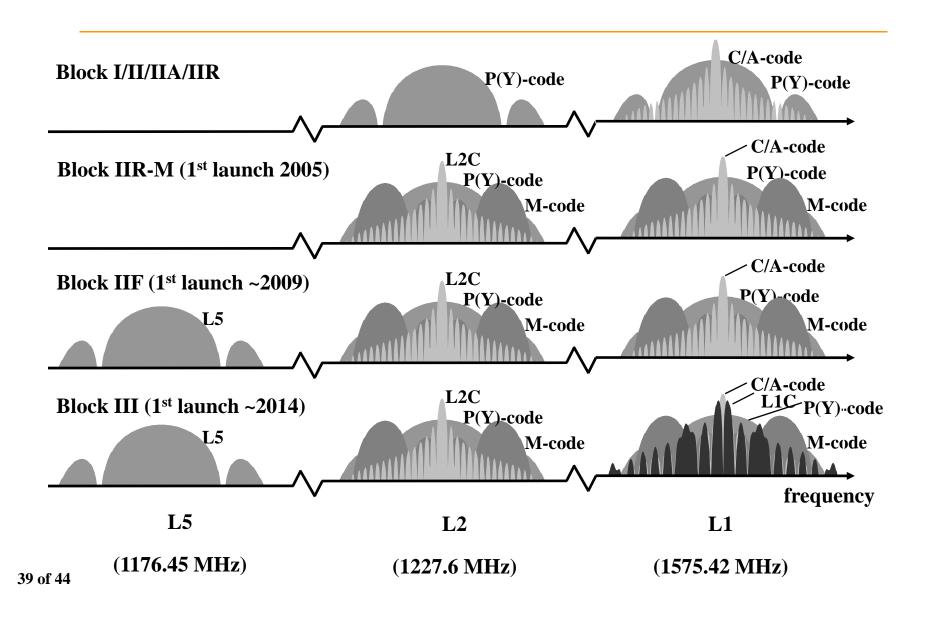
- Current receivers use the L1 frequency (1575.42 MHz)
 - Measures the range from each satellite
 - Range measurement affected by atmosphere
 - WAAS error grid allows user to interpolate to correct for these errors
- Two signals on two frequencies allow the user to correct for atmospheric range errors
 - No interpolation
 - System can be much more robust to atmospheric disturbances
- Second frequency also gives protection against inadvertent radio frequency interference







GPS Signal Modernization



GPS Satellites

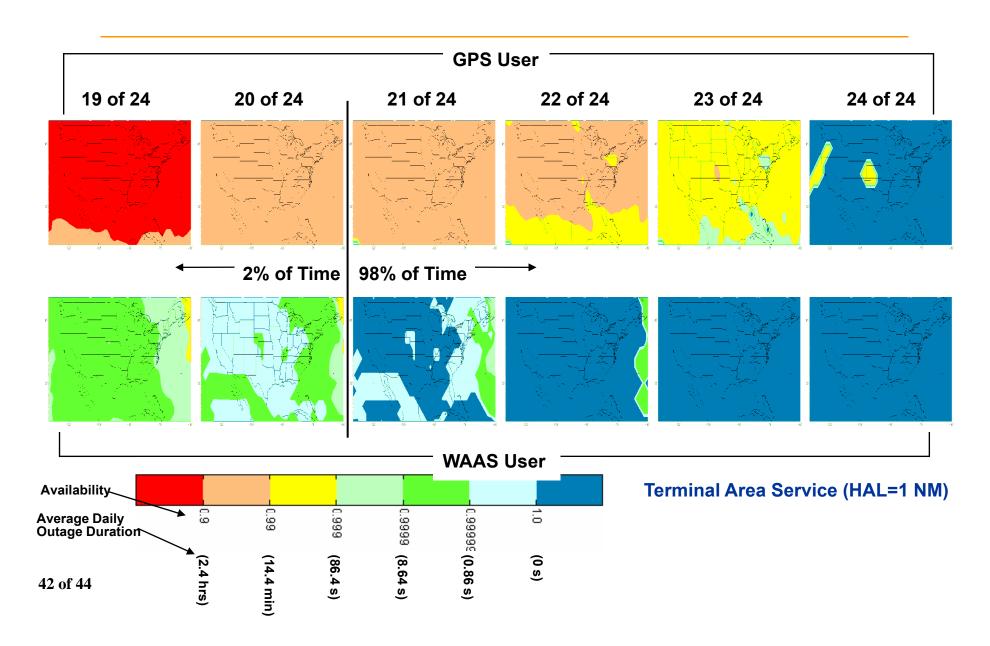
- 31 Operating satellites (IIA, IIR, IIR-Ms)
 - Many are "single string"
 - 32nd satellite (IIR-M) has some anomalies and is not yet operational after its March launch
- 1 more IIR-M ready for launch in August
- 12 IIF satellites are under contract by Boeing with first launch scheduled in January 2009
 - At least 3 years late with multiple problems and delays
- Contract for 12 GPS IIIa satellites just awarded to Lockheed Martin
 - First launch 2014 (faster planned development than IIFs)

GAO Report

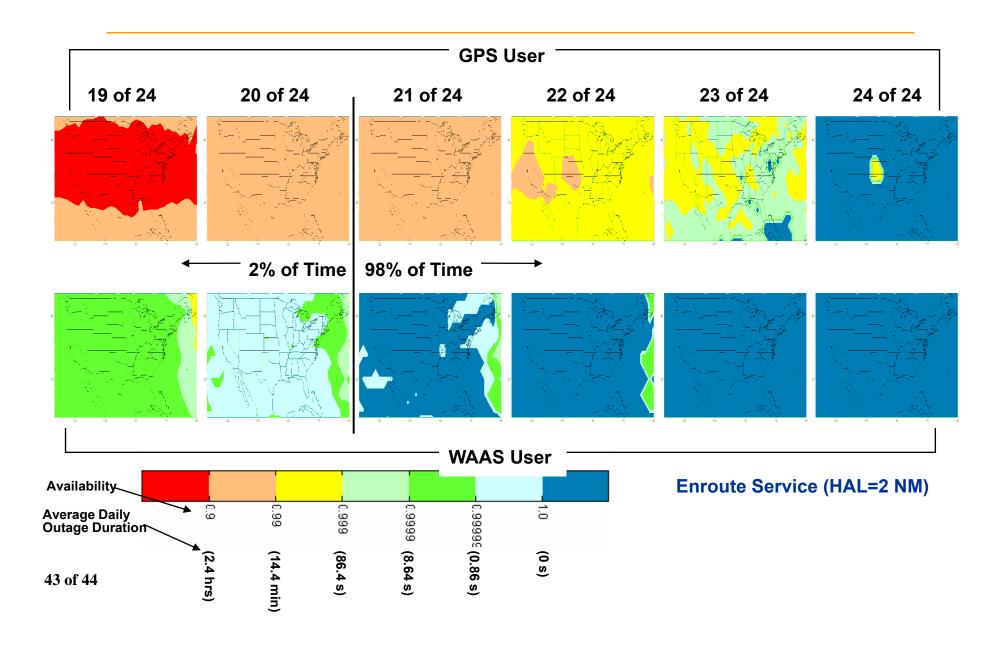
- IIF contract had many problems
 - Other U.S. space contracts have problems also
- Illa contract was awarded late and is compressed
 - 2014 launch may be optimistic
- Many flying satellites are old and 'single string'
- GAO Report:

"Based on the most recent satellite reliability and launch schedule data approved in March 2009, the estimated long-term probability of maintaining a constellation of at least 24 operational satellites falls below 95 percent during fiscal year 2010 and remains below 95 percent until the end of fiscal year 2014, at times falling to about 80 percent."

Availability of Terminal Service



Availability of Enroute Service



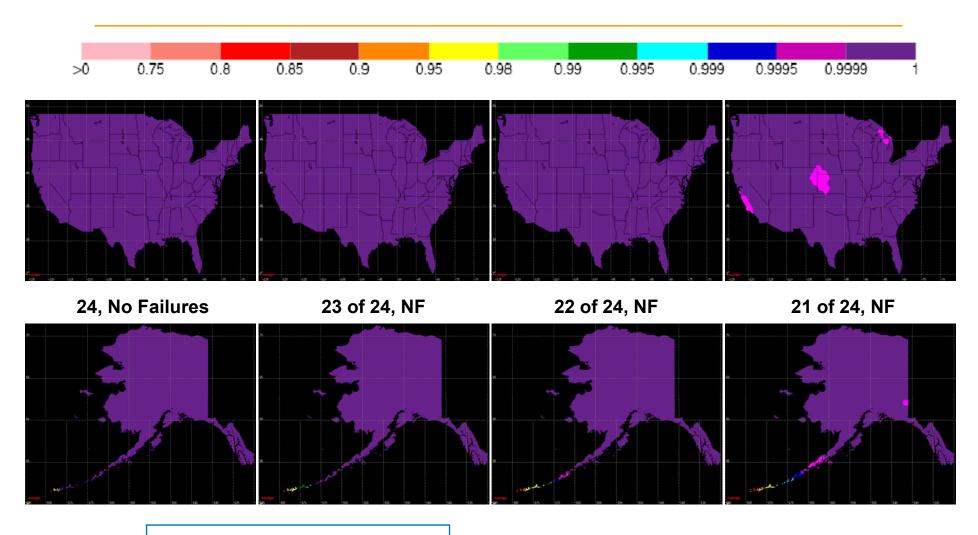
Contact Info

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- 703 983 7348
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- svm@mitre.org
- 703 983 5893

Backup Slides

WAAS Reduced Availability

LNAV (0.3 NM) with Western GEO Message and Ranging



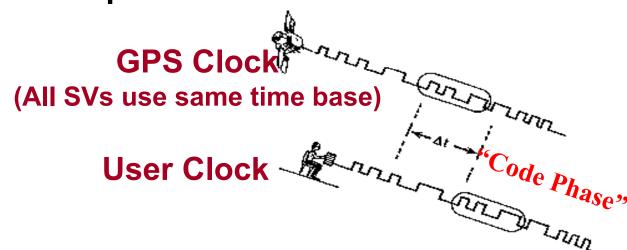
GEO @ 133 W, No GEO Failures

Current Positioning Systems

- Standard Positioning Service (SPS)
 - Single frequency receiver (L1)
 - C/A code and Nav/system data
- Precise Positioning Service (PPS)
 - Dual frequency receiver (L1 and L2)
 - Technical advantages to using two frequencies
 - C/A code, Nav/system data, and P(Y) code
 - Generally available to DOD and other approved users
 - Will not discuss further in this briefing

Range and Velocity Measurement (SPS)

- Each SV has a different 1023 bit pseudo random (PRN) code from which the user can determine the time of transmission
 - Repeats each millisecond
 - Continuous/passive--not like DME or radar
- User velocity can be measured from Doppler shift or from sequential position measurements



Position Measurement (Code Phase Tracking)

- Four unknowns
 - Latitude, longitude, altitude, receiver clock bias
- Four SVs required for xyz solution: receiver clock bias is corrected by finding unique position solution
 - SV time corrected for relativistic effects
 - Three SVs can give xy solution if altitude is known
- Accurate time provided to user

